Knowledge Engineering from Data Perspective: Granular Computing Approach

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KNOWLEDGE ENGINEERING FROM DATA PERSPECTIVE : GRANULAR COMPUTING APPROACH

A Thesis
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The Faculty of the Department of Computer Science
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of the Requirements for the Degree
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by
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ABSTRACT

KNOWLEDGE ENGINEERING FROM DATA PERSPECTIVE: GRANULAR COMPUTING APPROACH

by Rushin B. Barot

The concept of rough set theory is a mathematical approach to uncertainty and vagueness in data analysis, introduced by Zdzislaw Pawlak in 1980s. Rough set theory assumes the underlying structure of knowledge is a partition. We have extended Pawlak’s concept of knowledge to coverings. We have taken a soft approach regarding any generalized subset as a basic knowledge. We regard a covering as basic knowledge from which the theory of knowledge approximations and learning, knowledge dependency and reduct are developed.
DEDICATION

This research is dedicated to all the researchers who have contributed in the field Machine Learning. I got the opportunity to work on this research because of their contribution.

In addition, I would also like to dedicate this work to all the readers.
ACKNOWLEDGEMENTS

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Theory of knowledge has a long and rich history. Artificial Intelligence and logicians have been involved in various aspects of the knowledge. As per Pawlak, knowledge is deep-seated in the classificatory abilities of human beings and other species. Pawlak has introduced a rough set concept as a theoretical framework for discussions about knowledge, particularly when imprecise knowledge is of primary concern.

Pawlak assumes that knowledge is the ability to classify objects; so a knowledge is a mathematical partition. Thus knowledge is connected to varieties of classifications related to specific parts of the real or abstract world, called universe of discourse [Paw82].

Pawlak’s method is limited to partition. But in real life, classifications have never been perfect. We consider the covering, in which the conditions of mutual disjointness are not required.

1.1 Knowledge based on covering

A collection of subset is called a partial covering. If the union of a partial covering is the whole space, then the partial covering is called covering. Suppose we have given finite set $U \neq \emptyset$ objects. Any subset $X \subseteq U$ of the universe will be called
a concept in $U$. The given covering on $U$ will be referred to as given Basic Knowledge about $U$.

Suppose we have some families of covering over $U$. i.e the collection $\mathcal{C} = \{C_1, C_2, ..., C_m\}$ . Here $\mathcal{C}$ is called collection of families of subsets, where $C_1 = \{C_{11}, C_{12}, C_{13}, ..., C_{1n_1}\}$, $C_2 = \{C_{21}, C_{22}, C_{23}, ..., C_{2n_2}\}$ up-to $C_m = \{C_{m_1}, C_{m_2}, C_{m_3}, ..., C_{mn_m}\}$. Here $C_j$ is a family of subsets, such that $C_{ji} \subseteq U$, $C_{ji} \neq \emptyset$ and $\bigcup C_{ji} = U$, where $j = 1, 2, ..., m$ and $i = 1, 2, ..., n$ with respect to $j$. From this covering $\mathcal{C}$ we can derive a new covering $\mathcal{G}$ by AND operation. Here $\mathcal{G} = \{G_1, G_2, ..., G_m\}$, where $G_j = \cap_{(finitely\ many\ i)}C_{ji} \neq \emptyset$.

So $(U, \mathcal{G})$ and $(U, \mathcal{C})$ will be referred to knowledge base. We are going to consider three knowledge base a) Pawlak Partition Knowledge Base (PPKBS), b) Pawlak Covering Knowledge Base (PCKBS) and c) General Covering Knowledge Base (GCKBS).

PCKBS only use all $(\cup)$ to approximate an arbitrary concept while GCKBS use all $(\cup)$ and $(\cap)$. 
CHAPTER 2

MACHINE LEARNING

2.1 Introduction

Classification and categories has been crucial concept in the knowledge theory. Categories are defined in available knowledge in the given knowledge base. In a knowledge base some categories can be defined however some categories cannot. In other words we will discuss about vagueness of the categories.

2.2 Rough Sets

Let $X \subseteq U$, and $R$ be an equivalence relation. We can say that $X$ is R-definable, iff $X$ is the union of some R-basic categories; otherwise $X$ is R-undefinable.\cite{Paw82} The sets which can be defined in R by the given knowledge base are also called as R-exact set. The sets which cannot be defined in R by the given knowledge base are also called as R-inexact or R-rought sets. The figure 2.1 defines lower approximation and upper approximation.

2.3 Approximation of Set

This section describes theory of single covering or partition. Let knowledge base $(U, P)$, $(U, C)$ and $(U, G)$ be approximation spaces for PPKBS, PCKBS and GCKBS respectively.
Figure 2.1: Rough Sets with lower bound and upper bound.
2.3.1 Approximation theory based on PPKBS

Pawlak uses approximation to express unknown concepts by available knowledge. Pawlak reveals approximation as learning. Its goal is to learn every concept in the universe. If a concept can be learnt precisely then it is called an exact concept. If we cannot learn a concept precisely then we have approximation.

As per Pawlak’s theory, based on partition of certain universe $U$, which has a family of subset $P = \{P_1, P_2, ..., P_n\}$ be the partition. A partition is collection of mutually disjoint subsets, so for given knowledge base $K = (U, P)$. Let $X$ be the subset of $U$.

$$\underline{PX} = \{z \mid \exists P_i \in P, \text{ s.t. } z \in P_i \text{ and } P_i \subseteq X\}$$

$$\overline{PX} = \{z \mid \forall P_i \in P, \text{ s.t. } z \in P_i \text{ and } P_i \cap X \neq \emptyset\}$$

called the $P$ - lower and $P$-upper approximation of $X$ respectively [Paw82].

2.3.2 Approximation theory based on PCKBS

In PCKBS, we have given knowledge base $K = (U, C)$ with each subset $X \subseteq U$ and a family of subset $C \in C$. Here $C_i$ is any member of covering $C$.

$$\underline{CX} = \{z \mid \exists C_i \in C, \text{ s.t. } z \in C_i \text{ and } C_i \subseteq X\}$$

$$\overline{CX} = \{z \mid \forall C_i \in C, \text{ s.t. } z \in C_i \text{ and } C_i \cap X \neq \emptyset\}$$

called the $C$ - lower and $C$-upper approximation of $X$ respectively.
2.3.3 Approximation theory based on GCKBS

In GCKBS, we have used AND and OR operation for basic knowledge. Our approximation is different from Pawlak. Suppose we are given a knowledge base $K = (U, G)$ with each subset $X \subseteq U$ and a family of covering $G \in \mathcal{G}$, where $G$ is any family of subsets from $\mathcal{G}$ and $G_i$ is a member of family of family of subsets.

$$G X = \{ z \mid \exists G_i \in G, \text{ s.t. } z \in G_i \text{ and } G_i \subseteq X \}$$

$$\overline{G} X = \{ z \mid \forall G_i \in G, \text{ s.t. } z \in G_i \text{ and } G_i \cap X \neq \emptyset \}$$

called the $G$ - lower and $G$-upper approximation of $X$ respectively.

2.3.4 *

Theorem :

(1) Approximation space based on GCKBS is topological space.

(2) Approximation space based on PCKBS may not be topological space.

(3) Approximation based on PPKB is clopen topological space.

Case 1) Approximation spaces is a topological space generated by sub-base $C$ or equivalently generated by base $G$.

Case 3) Equivalence class is based on topological spaces.

Pawlak’s rough set theory is a special type of clopen(close and open) space. This is generalization of Pawlak’s approximation theorem. We have demonstrated the concept using an example below.
2.3.5 Proposition

(1) X is R-definable if and only if $R_X = RX$.

(2) X is rough with respect to R if and only if $R_X \neq RX$.

Example

Suppose we have given the following set, $U = \{x_1, x_2, x_3, x_4, x_5, x_6, x_7, x_8\}$.

In our example we have used $C = \{C_1\}$ and $C_1 = \{C_{11}, C_{12}, C_{13}, C_{14}, C_{15}\}$. Suppose we have given knowledge base $(U, C_1)$ and we have family of subset of subset

$$
c_{11} = \{x_1, x_2, x_3, x_4\}
c_{12} = \{x_3, x_4, x_5\}
c_{13} = \{x_5, x_6, x_2\}
c_{14} = \{x_6, x_7, x_8\}
c_{15} = \{x_7, x_8, x_1\}.
$$

Here family of subset of subset is basic knowledge or covering base space. Now we have $G_1$ which is finite intersections of covering $C_1$ set. So
which is also called categories of covering. Therefore, distinct elements of set
\[ G_1 = \{G_{11}, G_{12}, G_{13}, G_{14}, G_{15}, G_{16}, G_{17}, G_{18}, G_{19}, G_{110}, G_{113}, G_{115}\}. \]

We can see that our basic knowledge is much bigger than Pawlak’s basic knowledge.
Pawlak’s knowledge base is special case in covering base.

Let \( K = (U, C_1) \) be the knowledge base over \( U \) and \( G_1 \) can be generated from \( C_1 \). \( G_1 \) is
finite intersections from covering $C_1$. Let $X_1 = \{x_1, x_2, x_3, x_4\}$ and $X_2 = \{x_1, x_6, x_7\}$.

\[
G_X X_1 = G_{x_1} \cup G_{x_6} \cup G_{x_7} \cup G_{x_9} = \{x_1, x_2, x_3, x_4\}
\]

\[
\overline{G} X_1 = G_{x_1} \cup G_{x_6} \cup G_{x_7} \cup G_{x_9} = \{x_1, x_2, x_3, x_4\}
\]

here $X_1$ is called an exact set.

\[
G_X X_2 = G_{x_1} \cup G_{x_6} \cup G_{x_9} = \{x_1, x_6\}
\]

\[
\overline{G} X_2 = \{x_1, x_2, x_3, x_4, x_5, x_6, x_7, x_8\}
\]
CHAPTER 3

REDUCTION OF KNOWLEDGE

3.1 Introduction

A fundamental problem is whether the whole knowledge is always necessary to define some categories available in the knowledge being considered. This problem arises in many practical applications and will be referred to as knowledge reduction. Knowledge dependency plays key role in reduction of knowledge. Here we have considered several covering or partition as knowledge space.

3.2 Reduct and Core of Knowledge

There are two fundamental concepts, a reduct and the core. A reduct of knowledge essentially reduces the knowledge without compromising the knowledge base. From Reduct we can also generate original knowledge base. In short, reduct is essential part of knowledge, if we loose data from reduct we cannot reproduce the original knowledge, whereas the core is the most important part of the knowledge.

Let $G = (R, S)$ be the family of covers. If $\bigcap(G) \neq \bigcap(G - \{R\})$ than $R$ is indispensable in $G$ and $R$ is dispensable if $\bigcap(G) = \bigcap(G - \{R\})$.

3.2.1 Proposition

\[ \text{CORE}(G) = \bigcap \text{RED}(G) \]
Where RED(\mathcal{G}) is the family of the all reducts of \mathcal{G}.

Example

Let \mathcal{G} = \{G_1, G_2, G_3\} be the family of covers, where

\[
U(G_1) = \{x_1, x_2, x_7\}, \{x_3, x_4, x_6\}, \{x_5, x_6\}, \{x_1\}
\]

\[
U(G_2) = \{x_1, x_3, x_7\}, \{x_1, x_2, x_5\}, \{x_4, x_6\}, \{x_4\}
\]

\[
U(G_3) = \{x_1, x_4, x_7\}, \{x_1, x_6\}, \{x_1, x_2\}, \{x_3, x_5\}, \{x_4, x_6\}
\]

So that

\[
U(\mathcal{G}) = \bigcap \mathcal{G} = \bigcap \{G_1, G_2, G_3\} =
\]

\[
\{x_1, x_7\}, \{x_1, x_2\}, \{x_4, x_6\}, \{x_1\}, \{x_3\}, \{x_4\}, \{x_5\}, \{x_6\}\]

Here the relation \(G_1\) is indispensable in \(\mathcal{G}\) since,

\[
U(\mathcal{G} - \{G_1\}) = \{x_1, x_2\}, \{x_1, x_7\}, \{x_4, x_6\}, \{x_1\}, \{x_2\}, \{x_3\}, \{x_4\}, \{x_5\}, \{x_6\}\}

\neq U(\mathcal{G})

Similarly for relation \(G_2\),

\[
U(\mathcal{G} - \{G_2\}) = \{x_1, x_2\}, \{x_1, x_7\}, \{x_4, x_6\}, \{x_1\}, \{x_3\}, \{x_4\}, \{x_5\}, \{x_6\} = U(\mathcal{G})
\]

so cover \(G_2\) is dispensable in \(\mathcal{G}\) and for cover \(G_3\) we have

\[
U(\mathcal{G} - \{G_3\}) = \{x_1, x_7\}, \{x_1, x_2\}, \{x_4, x_6\}, \{x_1\}, \{x_3\}, \{x_4\}, \{x_5\}, \{x_6\} = U(\mathcal{G})
\]

hence the relation \(G_3\) is dispensable in \(\mathcal{G}\).

Here classification deduced by the covers \(G_1, G_2, G_3\) is same as the classification deduced by the cover \(G_1\) and \(G_2\) or \(G_1\) and \(G_3\). So the reduct of the knowledge base \(U(G_1, G_2) \neq U(G_1)\) and \(U(G_1, G_2) \neq U(G_2)\) concludes that \(G_1\) and \(G_2\) are not dependent. We have two reducts of \(\mathcal{G}\) which are \(\{G_1, G_2\}\) and \(\{G_1, G_3\}\).

As per proposition, \(\{G_1, G_2\} \cap \{G_1, G_3\} = \{G_1\}\) is a core of the \(\mathcal{G}\).
3.3 Reduction of Categories

A reduct of knowledge is its essential part, which suffices to define all basic concepts occurring in the considered knowledge, whereas the core is in a certain sense its most important part.

Reduct of family of sets: Let \( F = \{C_1, C_2, ..., C_n\} \), be a family of sets such that \( C_i \subseteq U \).

We say that \( C_i \) is dispensable in \( F \), if \( \bigcap(F - \{C_i\}) = \bigcap F \); otherwise the \( C_i \) is indispensable in \( F \).

The family \( F \) is independent if all of its components are indispensable in \( F \); otherwise \( F \) is dependent.

The family \( H \subseteq F \) is a reduct of \( F \), if \( H \) is independent and \( \bigcap H = \bigcap F \).

The family of all indispensable sets in \( F \) will be called the core of \( F \), denoted \( \text{CORE}(F) \).

3.3.1 Proposition

\[ \text{CORE}(F) = \bigcap \text{RED}(F) \]

where \( \text{RED}(F) \) is the family of all reducts of \( F \).

Example

Suppose we have family of sets \( F = \{C_1, C_2, C_3\} \), where
\[ C_1 = \{C_{11}, C_{12}\} \]
\[ C_2 = \{C_{21}, C_{22}\} \]
\[ C_3 = \{C_{31}, C_{32}\} \]

where

\[ C_{11} = \{x_1, x_2, x_3, x_4\} \]
\[ C_{12} = \{x_4, x_5\} \]
\[ C_{21} = \{x_1, x_2, x_5\} \]
\[ C_{22} = \{x_3, x_4\} \]
\[ C_{31} = \{x_1, x_2, x_4\} \]
\[ C_{32} = \{x_3, x_4, x_5\} \]

\[ \text{Hence } \bigcap F = C_1 \cap C_2 \cap C_3 = \{\{x_1, x_2\}, \{x_3, x_4\}, \{x_4\}, \{x_5\}\} \]

because the relations

\[ \bigcap (F - \{C_1\}) = C_2 \cap C_3 = \{\{x_1, x_2\}, \{x_3, x_4\}, \{x_4\}, \{x_5\}\} \]
\[ \bigcap (F - \{C_2\}) = C_1 \cap C_3 = \{\{x_1, x_2, x_4\}, \{x_3, x_4\}, \{x_4, x_5\}, \{x_4\}\} \]
\[ \bigcap (F - \{C_3\}) = C_1 \cap C_2 = \{\{x_1, x_2\}, \{x_3, x_4\}, \{x_3\}, \{x_4\}\}. \]

In order to find reducts of the family of \( F = \{C_1, C_2, C_3\} \). From the covering \( C_1, C_2, C_3 \) we can say that \( C_1 \) is dispensable in family of \( F \), hence the reduct of \( F \) are \( \{C_1, C_2, C_3\} \) and \( \{C_2, C_3\} \). Thus two reducts of family \( F \), namely \( \{C_1, C_2, C_3\} \) and \( \{C_2, C_3\} \) and \( \{C_1, C_2, C_3\} \cap \{C_2, C_3\} = \{C_2, C_3\} \) is the core of family \( F \).
4.1 Introduction

In knowledge dependency we have shown the semantic aspects of dependency. In the following, we need the notion of knowledge dependency; it has two notions, weak dependency (WD) and strong dependency (SD). Without specification, we define this knowledge dependency as follows:

(1) Knowledge $Q_X$ depends on knowledge $P_X$ iff $P_X \subseteq Q_X$ is called weak dependency (WD).

(2) Knowledge $Q_X$ depends on knowledge $P_X$ iff $\bigcup P_X = Q_X$ is called strong dependency (SD).

where the inclusion ($\cap$) and union ($\cup$) will be clearly defined in each section. Here $X$ can be Partition ($P$), Pawlak Covering ($C$) or General covering ($G$).

The following are three cases of knowledge dependency.

4.1.1 Knowledge Dependency based on PPKBS

As per Pawlak’s theory, dependency for partition has the following property. Let $K = (U, \mathcal{P})$ be knowledge base and let $P, Q \subseteq \mathcal{P}$. In this case, $X$ is partition in
given definition of knowledge dependency.

We have observed following properties of PPKBS

A) Knowledge P and Q are PPKBS. WD = SD.

B) $P_1 \cap P_2 \Rightarrow P_1$ and $P_1 \cap P_2 \Rightarrow P_2$.

Suppose equivalence classes from a partition $P_1 = \{P_{11}, P_{12}, \ldots, P_{1n}\}$. Let $P_{1i}$ be any equivalence class from a family of set $P_1$, where index $i = 1, 2, \ldots, n$. $P_2 = \{P_{21}, P_{22}, \ldots, P_{2m}\}$, where $P_{2j}$ be the any equivalence class from a family of set $P_2$, where index $j = 1, 2, \ldots, m$. Partitions $P_1$ and $P_2$ are over $U$.

Let say we choose a equivalence class $P_{1i}$ from $P_1$. It is a partition, so there is no other same elements in any other equivalence class in $P_1$. Now if we check all the equivalence classes of $P_2$. There has to be some equivalence classes where $P_{2j} \cap P_{1i} \neq \emptyset$. We have $k$ number of equivalence classes from $P_2$, so $k \leq j$, which is $\bigcup_{k=1}^{n} P_{2k}$.

$P_{1i} \subset \left(\bigcup_{k=1}^{n} P_{2k}\right)$, $P_{1i} \cap \left(\bigcup_{k=1}^{n} P_{2k}\right) = P_{1i}$, so that we can say that $P_1 \cap P_2 \Rightarrow P_1$. We can say same as for $P_1 \cap P_2 \Rightarrow P_2$.

C) $P_1 \Rightarrow P_1 \cup P_2$ and $P_2 \Rightarrow P_1 \cup P_2$.

$P_1 \cup P_2$ is a smallest partition that contains $P_1$ and $P_2$. Let $X$ be the equivalence class of new partition $P_1 \cup P_2$ such that $P_{1j}$ contains in $X$, so $P_{1j} \subset X$. We can say that $P_1 \Rightarrow P_1 \cup P_2$, same way we can show for $P_2 \Rightarrow P_1 \cup P_2$.

The following example will demonstrate the above properties.

**Example**

Suppose we have a family for subsets $P_1, P_2$, where $P_1 = \{P_{11}, P_{12}\}$ and $P_2 =$
\{P_{21}, P_{22}\}.

\begin{align*}
P_{11} &= \{x_1, x_2, x_3\} \\
P_{12} &= \{x_4, x_5, x_6\} \\
P_{21} &= \{x_1, x_2\} \\
P_{22} &= \{x_3, x_4, x_5, x_6\}
\end{align*}

so followings are intersection properties

\begin{align*}
P_{11} \cap P_{21} &= \{x_1, x_2\} \\
P_{11} \cap P_{22} &= \{x_3\} \\
P_{12} \cap P_{21} &= \emptyset \\
P_{12} \cap P_{22} &= \{x_4, x_5, x_6\}
\end{align*}

\begin{align*}
P_{11} \cap P_{21} &\subset P_{11} \\
P_{11} \cap P_{22} &\subset P_{11} \\
P_{12} \cap P_{21} &\subset P_{12} \\
P_{12} \cap P_{22} &\subset P_{22}
\end{align*}

same as

\begin{align*}
P_{11} \cap P_{21} &\subset P_{21} \\
P_{11} \cap P_{22} &\subset P_{22} \\
P_{12} \cap P_{22} &\subset P_{22}
\end{align*}

so that we can say that \(\forall P_i, \exists P_i \cap P_j \subset P_i\).
\[(P_{11} \cap P_{21}) \cup (P_{11} \cap P_{22}) = P_{11}\]
\[(P_{22} \cap P_{21}) \cup (P_{21} \cap P_{22}) = P_{12}\]
\[(P_{11} \cap P_{21}) = P_{21}\]
\[(P_{11} \cap P_{22}) \cup (P_{12} \cap P_{22}) = P_{22}\]

We can say that both weak dependency and strong dependency holds true.

\[P_{11} \cup P_{21} = \{x_1, x_2, x_3\}\]
\[P_{11} \cup P_{22} = \{x_1, x_2, x_3, x_4, x_5, x_6\}\]
\[P_{12} \cup P_{21} = \{x_1, x_2, x_4, x_5, x_6\}\]
\[P_{12} \cup P_{22} = \{x_3, x_5, x_6\}\]

In the above example we got only partition \((P_1 \cup P_2) = \{\{x_1, x_2, x_3, x_4, x_5, x_6\}\}\), which satisfy that for all equivalence classes of partitions \(P_1\) and \(P_2\) is subset of equivalence class of partition \((P_1 \cup P_2)\).

### 4.1.2 Knowledge Dependency based on PCKBS

Let \(K = (U, C)\) be knowledge base and let \(C, D \subseteq C\). In PCKBS, \(X\) is Pawlak’s theory covering in given knowledge dependency definition.

We observe following properties for PCKBS:

D) \(C_1 \cap C_2 \Rightarrow C_1\) and \(C_1 \cap C_2 \Rightarrow C_2\)
Suppose all the member’s from $C_1 = \{C_{11}, C_{12}, ..., C_{1n}\}$. Let $C_{1i}$ be the any member from a family of set $C_1$, where index $i = 1, 2, ..., n$. As covering $C_1$ and $C_2$ are over $U$. $C_2 = \{C_{21}, C_{22}, ..., C_{2m}\}$, where $C_{2j}$ be the any member a family of set $C_2$, where index $j = 1, 2, ..., m$.

Let say we choose one member $C_{1i}$ from $C_1$. It is covering so there may or may not be other member in $C_1$. If we check all the members of $C_2$. There has to be some members, where $C_{2j} \cap C_{1i} \neq \emptyset$. Consider $k$ number of members from $C_2$, where $k \leq j$, which is $\bigcup_{k=1}^{n} C_{2k}$. $C_{1i} \subset (\bigcup_{k=1}^{n} C_{2k})$, $C_{1i} \cap (\bigcup_{k=1}^{n} C_{2k}) = C_{1i}$. We can say that $C_1 \cap C_2 \Rightarrow C_1$. We can show same as $C_1 \cap C_2 \Rightarrow C_2$.

E) $C_1 \Rightarrow C_1 \cup C_2$ and $C_2 \Rightarrow C_1 \cup C_2$

$C_1 \cup C_2$ is a smallest covering that contains $C_1$ and $C_2$. Let X be the member of new covering $C_1 \cup C_2$ such that $C_{1j}$ contains in X. So $C_{1j} \subset X$. So we can say that $C_1 \Rightarrow C_1 \cup C_2$. We can prove for $C_2 \Rightarrow C_1 \cup C_2$.

These property can be easily understand from the below example.

**Example**

Suppose we have a family of covering $C_1$ and $C_2$, where $C_1 = \{C_{11}, C_{12}\}$ and $C_2 = \{C_{21}, C_{22}\}$.

The elements of subsets $C_{11}$, $C_{12}$, $C_{21}$ and $C_{22}$ are below:

- $C_{11} = \{x_1, x_2, x_3\}$
- $C_{12} = \{x_2, x_4, x_5, x_6\}$
- $C_{21} = \{x_1, x_2, x_6\}$
- $C_{22} = \{x_3, x_4, x_5, x_6\}$
So followings are intersection of subsets of covering

\[ C_{11} \cap C_{21} = \{x_1, x_2\} \]

\[ C_{11} \cap C_{22} = \{x_3\} \]

\[ C_{12} \cap C_{21} = \{x_2, x_6\} \]

\[ C_{12} \cap C_{22} = \{x_4, x_5, x_6\} \]

\[ (C_{11} \cap C_{21}) \cup (C_{11} \cap C_{22}) = C_{11} \]

\[ (C_{12} \cap C_{21}) \cup (C_{12} \cap C_{22}) = C_{12} \]

\[ (C_{11} \cap C_{21}) \cup (C_{12} \cap C_{21}) = C_{21} \]

\[ (C_{11} \cap C_{22}) \cup (C_{12} \cap C_{22}) = C_{22} \]

Therefore, strong dependency holds true for the Pawlak’s covering.

\[ C_{11} \cup C_{21} = \{x_1, x_2, x_3, x_6\} \]

\[ C_{11} \cup C_{22} = \{x_1, x_2, x_3, x_4, x_5, x_6\} \]

\[ C_{12} \cup C_{21} = \{x_1, x_2, x_4, x_5, x_6\} \]

\[ C_{12} \cup C_{22} = \{x_2, x_3, x_4, x_5, x_6\} \]

Lets say \( C_{31} = \{x_1, x_2, x_3\} \). We check for some category \( C_2 \subseteq C_{31} \). In our case we don’t find any categories in \( C_2 \). We include new element in \( C_{31} \), which can satisfy for any categories in \( C_1 \subseteq C_3 \) and \( C_2 \subseteq C_3 \). Continuing this process, we get the new covering \( C_3 \) which satisfies for both covering \( C_1 \) and \( C_2 \). So in above example we got new cover \( C_3 = \{\{x_1, x_2, x_3, x_4, x_5, x_6\}\} \).
4.1.3 Knowledge Dependency based on GCKBS

Let $K = (U, \mathcal{G})$ be knowledge base and let $G_1, G_2 \subseteq \mathcal{G}$. Here $G_1$ and $G_2$ are finite intersections of family of covering $C$ and $D$ respectively. $X$ is General Covering in the definition of knowledge dependency.

More Precisely, knowledge $G_2$ is derivable from knowledge $G_1$, if all member of $G_2$ can be defined in terms of some member of knowledge $G_1$. If $G_2$ is derivable from $G_2$, we will also say that $G_2$ depends on $G_1$ and can be written as $G_1 \Rightarrow G_2$.

We observe following properties:

F) $G_1 \cap G_2 \Rightarrow G_1$ and $G_1 \cap G_2 \Rightarrow G_2$

Suppose all the member from $C_1 = \{C_{11}, C_{12}, ..., C_{1n}\}$. Let $C_{1i}$ be the any member from a family of set $C_1$, where index $i = 1, 2, ..., n$. Covering $C_1$ and $C_2$ are over $U$. $C_2 = \{C_{21}, C_{22}, ..., C_{2m}\}$, where $C_{2j}$ be the any categories a family of set $C_2$, where index $j = 1, 2, ..., m$. $G_1$ is finite intersections of $C_1$ and $G_2$ is finite intersections of $C_2$.

Let say we choose one member $G_{1i}$ from $G_1$. It is covering so there may or may not be other member in $G_1$, which satisfy $G_{1j} \subset G_{1i}$. However we know that there is at least one member who satisfy $G_{1i} \subset G_1$. If we check all the members of $G_2$. There have to be some members, where $G_{2j} \cap G_{1i} \neq \emptyset$. Consider $k$ number of members from $G_2$, where $k \leq j$, which is $\bigcup_{k=1}^{n} G_{2k}$.

$G_{1i} \subset (\bigcup_{k=1}^{n} G_{2k})$. Consequently $G_{1i} \cap (\bigcup_{k=1}^{n} G_{2k}) = G_{1i}$. We can say that $G_1 \cap G_2 \Rightarrow G_1$. Therefore, we can prove same as $G_1 \cap G_2 \Rightarrow G_2$.

G) $G_1 \Rightarrow G_1 \cup G_2$ and $G_2 \Rightarrow G_1 \cup G_2$.

$G_1 \cup G_2$ is a smallest covering that contains $G_1$ and $G_2$. Let $X$ be the member of
new covering $G_1 \cup G_2$ such that $G_{1j}$ contains in $X$. Consequently $G_{1j} \subset X$. Therefore, we can say that $G_1 \Rightarrow G_1 \cup G_2$. Similarly, we can say for $G_2 \Rightarrow G_1 \cup G_2$. 
CHAPTER 5

KNOWLEDGE REPRESENTATION

5.1 Introduction

A n-dimensional Euclidean space is the Cartesian product of n copies of real numbers. A unit point is a point whose co-ordinates are all 1 but one single 0, (1, ..., 0, 1, ..., 1). These unit points can be viewed as vertices. Here we will explain in depth about n-simplex. These unit points will be regarded as vertices. We will use them to illustrate the notion of n-simplex.

Let us examine the $n - simplex es$, when $n = 0, 1, 2, 3$. 0-simplex $\Delta (\emptyset_0)$ consists of a vertex $\emptyset_0$, which is a point in Euclidean space. 1-simplex $\Delta (V_0, V_1)$ consists of two points $V_0, V_1$. These two unit points can be explained as $(V_0, V_1)$ an open segment in Euclidean space; However we did not include its end points. 2-Simplex $\Delta (V_0, V_1, V_2)$ consists of three points $V_0, V_1, V_2$. These three points can be explained with vertices $V_0, V_1,$ and $V_2$ as an open triangle, which also does not include its vertices and edges. 3-Simplex $\Delta (V_0, V_1, V_2, V_3)$ has a four points $V_0, V_1, V_2, V_3$ that considered as an open tetrahedron. Again, its boundaries has not been included.

Formally, we can say that the points in Euclidean space can be any kind of objects but could not be vertices.

Definition 1: A n-simplex, denoted by $\Delta (V_0, ..., V_n)$ is a set of independent abstract vertices $V_0, ..., \{V_n\}$. A $G - subset$ of a n-simplex is a G-simplex $\Delta (V_{j_0}, ..., V_{j_n})$
whose vertices are a subset of $V_0, \ldots, V_n$ with cardinality $G + 1$.

**Definition 2**: Simplex can be defined as single vertex has any set. Closed condition can be defined as simplex without empty set of subset. Here we conceives simplicial complex with vertices and subsets of finite numbers of set.

$G$ - *simplex* is simplex $S$ who has exact one more vertices. There are also the dimension of $s$ so that we could write $\text{dims} = G$. and it is also interpreted as non-closed simplical complex.

Let us calculate any set of elements $k+1$ can be explained as set of abstract vertices. We can define simplex as maximal only iff the simplex can not be a face of other simplexes. The $k$-complex can be defined as the maximal dimension of the constituting simplexes is $k$.

### 5.2 Granular Structure

**Definition 3**: Global granular space can be defined as a granular model set $(U, B)$ where $B$ is family of subsets $X_j, j \in J$. and $U$ is knowledge is connected to varieties of classifications related to specific parts of the real or abstract world. Here $J$ can be regard as an index set.

**Examples on Intervals** Granular Model of a Covering

$U_1 = (-3, 3)$, the open interval of real line. $B_1$ is the covering, $((-3, 1), (-1, 3), (-2, 2)$

We name these intervals by $x, y, z$ in the order listed. This covering is not a partition, we have the following intersections

1. $x \cap y = (-1, 1)$
2. $x \cap z = (-2, 1)$
3. $y \cap z = (-1, 2)$
4. $x \cap y \cap z = (-1, 1)$
So $B_1$ generated a family of non-empty granules, $B = a, b, c, ab, ac, bc, abc$, where ∩ has been compressed.

Now we will consider the concept of the closed triangle, where it has two-dimensional simplicial complex. Now by interpretation of points $x = (1, 0, 0), y = (0, 1, 0)$ and $z = (0, 0, 1)$, where each intersection can be viewed as open segment of the two points. We can consider open segment $xy$, $xz$ and $yz$ and all three points can be viewed as open triangle.

**Example** Granular model of a partition.

Let us have another example of $B U_2 = (-3,3)$, $B_2 = (-3,-2), [-2,1), [-1,1), [1,2), [2,3)$

We have $x, y, z, a, b$ as clo-open intervals respectively and this partitions has intersection which are no-empty.

We can define quotient structure as a set of granules in discrete set.

### 5.3 The Granular Structure of a Covering

Let $B = B_j | j = 0, 1, ..., n$ is the finite set of cover $U$. In order to understand this we will consider set $B$, which is combinatorial topology:

1. $V_{\text{granule}} = B_j | j = 0, 1, 2, ..., n$ is the granular vertices which is interpreted as abstract vertices.

2. A subfamily $\{B_{jk}, k \in J\}$ can be called as a granular-simplex iff it has no-empty intersection or granules. In notations, $B_{jk}, k \in J = B_{jk} \cap_{k \in J} B_{jk} \neq \emptyset$

$S_{\text{granule}}$ can be interpreted as set of abstract simplex.

**Theorem** The pair $(V_{\text{granule}}, S_{\text{granule}})$ is an Abstract Simplical Complex.

Granular Simplical Complex (GSC) can be easily understand by the family of
non-empty granular points who has no-empty intersections to meet closed object. It is also considered as important part of $V_{\text{granule}}$.

**Theory** GSC can be considered as quotient structure iff $B$ is a partition and if $B$ is a partition, $V_{\text{granule}} = S_{\text{granule}}$ and GSC has only 0-simplexes.

This can be proof by $B$ is a partition, then the family $B_{jk}, k \in J = B_{jk} \cap k \in J_{jk} \neq \emptyset = \emptyset$, if the cardinality of $J \geq 2$. GSC is a set who has 0-simplexes.

### 5.4 Knowledge Representation Theory

The knowledge representation of a covering is a mapping, $K : U \rightarrow \beta; \rho \rightarrow \cap_i B_j$ where $\rho \in B_j$ for maximum number of $j$. The idea has be represented in the table. Let $U$ can be a set with a covering $\beta$ which has 12 basic granules, that is $\beta = \{a, b, c, d, e, f, g, h, w, x, y, z\}$.

![Figure 5.1: A complex with twelve vertexes.](image)

As we can see from the figure that each vertex can be interpreted as granules, if granules has edge connection iff two vertex has not null intersection. Similarly if
three vertex has non-empty intersection and three points are connected then it is an open triangles.

From the figure we can derive below intersections

\[ a \cap b \cap c \cap d \neq \emptyset; w \cap x \cap y \cap z \neq \emptyset; \] (5.1)
\[ a \cap c \cap h \neq \emptyset; c \cap e \cap h \neq \emptyset; \] (5.2)
\[ e \cap f \cap h \neq \emptyset; f \cap e \cap x \neq \emptyset; \] (5.3)
\[ f \cap g \cap x \neq \emptyset; x \cap y \cap g \neq \emptyset; \] (5.4)

The result can be shown in the table. For example, you can verify all the intersections given above from the table.
Table 5.1: The structure of the covering $\beta$

<table>
<thead>
<tr>
<th>Universe</th>
<th>Granules</th>
<th>Contents of granules</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>a</td>
<td>1,13,14</td>
</tr>
<tr>
<td>2</td>
<td>b</td>
<td>2,13</td>
</tr>
<tr>
<td>3</td>
<td>c</td>
<td>3,13,14,15</td>
</tr>
<tr>
<td>4</td>
<td>d</td>
<td>4,13</td>
</tr>
<tr>
<td>5</td>
<td>e</td>
<td>5,14,15,16</td>
</tr>
<tr>
<td>6</td>
<td>f</td>
<td>7,16,18</td>
</tr>
<tr>
<td>7</td>
<td>g</td>
<td>9,18,19</td>
</tr>
<tr>
<td>8</td>
<td>h</td>
<td>5,14,15,16</td>
</tr>
<tr>
<td>9</td>
<td>w</td>
<td>11,20</td>
</tr>
<tr>
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<td>x</td>
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</tr>
<tr>
<td>11</td>
<td>y</td>
<td>10,19,20</td>
</tr>
<tr>
<td>12</td>
<td>z</td>
<td>12,20</td>
</tr>
<tr>
<td>13</td>
<td>$a \cap b \cap c \cap d$</td>
<td>1</td>
</tr>
<tr>
<td>14</td>
<td>$a \cap c \cap h$</td>
<td>2</td>
</tr>
<tr>
<td>15</td>
<td>$c \cap e \cap h$</td>
<td>3</td>
</tr>
<tr>
<td>16</td>
<td>$e \cap f \cap h$</td>
<td>4</td>
</tr>
<tr>
<td>17</td>
<td>$f \cap e \cap x$</td>
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</tr>
<tr>
<td>18</td>
<td>$f \cap g \cap x$</td>
<td>6</td>
</tr>
<tr>
<td>19</td>
<td>$x \cap y \cap g$</td>
<td>7</td>
</tr>
</tbody>
</table>
CHAPTER 6

CONCLUSION

Rough Set Theory is a successful discipline in knowledge engineering. We extended Partition to Covering and Granulation.

However extension is a quantum jump:

- Approximation is viewed as learning theory.

- Classical Knowledge Representation is extended from set theory to algebraic theory.
BIBLIOGRAPHY


